

Application Note AN-102 InnoSwitch3-Pro/InnoSwitch4-Pro Family

Arduino Code Library Overview and Guide

Introduction

The application of InnoSwitch3-Pro and InnoSwitch4-Pro Family Arduino Library is discussed in this document. This code was designed to be highly portable with different microcontroller platforms. The use of Arduino compatible C++ language will make it easy for users to

InnoSwitch3-Pro

InnoSwitch3-Pro devices are ideal for AC/DC power supply applications where fine (10 mV, 50 mA) output voltage and current adjustment are necessary. Typical implementations comprise a system microprocessor or dedicated microcontroller with an I2C port that is used to configure,

understand and modify the code according to their needs. This guide will allow the user to get sufficient knowledge on how to operate the devices with a use of a simple microcontroller such as Arduino.

control and supervise the operation of the power sub-system. The uVCC pin provides a bias supply for the microprocessor in stand-alone implementations such as USB PD adapters and chargers.



InnoSwitch4-Pro

The command and telemetry registers on InnoSwitch4-Pro are updated compared to InnoSwitch3-Pro. These features add flexibility and improve

fault response.





System Requirements

Hardware

The InnoSwitch3-Pro and InnoSwitch4-Pro can be controlled using its on board microcontroller or by an external I²C Master through the interface header. This Demo Application does not use the on board microcontroller but an Arduino Uno as an I²C Master and InnoSwitch3-Pro/InnoSwitch4-

Pro as slave device. This demonstration will be conducted with the Reference Design RDK-641 for InnoSwitch3-Pro and RDR-961 for InnoSwitch4-Pro.



Figure 3. RDK-641

Number	Description	Label
1	AC Input Terminals	TP1, TP2
2	DC Output Terminals	TP3, TP4
3	uVcc and I ² C Isolation Jumpers	J3, J6, J7
4	PIC Programming Header	J5
5	Push Buttons	SW1, SW2
	Table 1. RDK-641 Part Description	on



Figure 4. DER-961

Number	Description	Label
1	AC Input Terminals	TP1, TP2
2	DC Output Terminals	TP3, TP4
3	uVcc and I ² C Isolation Headers	J2, J4, J6
4	External I ² C Interface Header	J3
	Table 2. RDR-961 Part Description	on



Arduino

Arduino IDE version 1.8.16 was used in this document with Arduino Mega 2560 microcontroller board because of its higher flash memory needed for other certain library examples. Arduino Uno board may also be used

for InnoSwitch3-Pro and InnoSwitch4-Pro library examples that do not require a lot of memory.



Figure 5. Arduino Mega 2560



Code Library

InnoSwitch3-Pro and InnoSwitch4-Pro Arduino code library contains the drivers and sketch examples of InnoSwitch3-Pro and InnoSwitch4-Pro. The function of these examples ranges from simply initializing the device up to allowing the user direct access to each individual Command and Telemetry registers. The InnoSwitch3-Pro and InnoSwitch4-Pro Arduino library can be downloaded from the link below.

InnoSwitch3-Pro and InnoSwitch4-Pro Family Code Library and API for Arduino | Power Integrations, Inc. https://www.power.com/design-support/downloads/innoswitch3-pro-

code-library-and-api-arduino

Library Installation

Head on to Arduino IDE and go to *Sketch menu > Include Library > Add*. *ZIP Library*. Select and open the Arduino .zip library. The user can check the if the library has been installed in the *Sketch menu > Include Library* menu. In addition, the library can also be seen in the file path below.

• C: |Users|username|Documents|Arduino|libraries|



Figure 6. Adding Arduino Library

Removing Other InnoSwitch3-Pro / InnoSwitch4-Pro Libraries

There is a need to remove older versions of the InnoSwitch3-Pro / InnoSwitch4-Pro Libraries since it may cause the Arduino IDE to compile the wrong source files with the new library. Using old source files may cause different issues and it is better to avoid that possibility by having only one version of the Arduino library. To remove other Arduino Libraries, sketch_jan22a | Arduino 1.8.16

go to the file path found in *File > Preferences* and delete the folder. In the example below, the file path is at *C: UsersUsersDocumentsArduino*. Go to the library and delete the folder of the old library likely named "InnoSwitch3-Pro_Library". This will avoid conflicting header files when compiling.

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Examples

Installing the library will allow the user to use the examples found in *File Sketchbook > InnoSwitch3-Pro and InnoSwitch4-Pro Library.* These sketches provide basic code and can serve as the framework and guide

more complex implementations for controlling InnoSwitch3-Pro and InnoSwitch4-Pro devices. Note that InnoSwitch3-Pro sketches do not work with InnoSwitch4-Pro devices and vice versa.

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InnoSwitch3-Pro Sketches

- Inno3Pro_APDOs.ino
- Inno3Pro_Basic.ino
- Inno3Pro_Basic_Volts_Amps_OV_UV.ino
- Inno3Pro_PD_Hard_Reset.ino
- Inno3Pro_PDOs.ino
- Inno3Pro_Plotter.ino
- Inno3Pro_Ramp.ino
- Inno3Pro_Random_Volt_Time.ino
- Inno3Pro_Serial.ino
- Inno3Pro_SineWave.ino

InnoSwitch4-Pro Sketches

- Inno4Pro_APDOs.ino
- Inno4Pro_Basic.ino
- Inno4Pro_Basic_Volts_Amps_OV_UV.ino
- Inno4Pro_PD_Hard_Reset.ino
- Inno4Pro_PDOs.ino
- Inno4Pro_Plotter.ino
- Inno4Pro_Ramp.ino
- Inno4Pro_Random_Volt_Time.ino
- Inno4Pro_Serial.ino
- Inno4Pro_SineWave.ino
- _



InnoSwitch3-Pro Examples

Example 1 - Inno3Pro_Basic.ino

Inno3Pro_Basic.ino sketch implements the essential commands to run the InnoSwich3-Pro IC. The adapter will output 5V 3.1A while using this code. There are five commands in this sketch to note:

- Inno3Pro_Initialization(); Function for initializing the InnoSwitch3-Pro device
- Inno3Pro_Write_VI(); Function for setting the output voltage and current
- Inno3Pro_Write_Volt_Peak(); Sets the knee voltage (V_{KP})
- Inno3Pro_Vbus_Switch_Control(); Controls the BUS switch

Example 2 - Inno3Pro_PDOs.ino

This sketch cycles through the multiple output voltages. This mimics the USBPD standard PDO's for 60W adapters. Main functions used:

- Inno4Pro_Initialization(); Initializes InnoSwitch4-Pro
- Inno4Pro_Write_Cable_Drop_Comp(); Sets the cable drop voltage in mV
- Inno4Pro_Write_Volt_Peak() Sets the knee voltage (V_{KP})
- Inno4Pro_Vbus_Switch_Control() Controls the BUS switch
- clock_HasTimeElapsedMs(); Returns 1 when a certain amount of time in milliseconds has elapsed.
- Clock_GetTimeStampMs(); Returns the current time in milliseconds
- Inno4Pro_PD_Write_VI(); Sets the output voltage and current





Figure 10. Inno3Pro_Basic.ino Code



```
#include <Drv_Rtc.h>
#include <Drv_i2c.h>
#include <InnoProBase.h>
#include "Inno3Pro.h'
#include "Inno3ProConfig.h"
//Step 2 : Create the class instance
InnoProBase_Rtc Inno3ProClk;
Inno3Pro_Application Inno3ProApp;
//Step 3 : Write Initial Commands to Inno Pro
void setup()
{
           Inno3ProApp.Inno3Pro_Initialization();
           Inno3ProApp.Inno3Pro_Write_Cable_Drop_Comp(300); // CDC = 300mV
Inno3ProApp.Inno3Pro_Write_Volt_Peak(24); // VKP = 24V
           Inno3ProApp.Inno3Pro_Vbus_Switch_Control(1);
                                                                // VBEN = ON
}
//Step 4 : Call the Functions on the Main Loop
void loop()
{
  // Main Loop Variables
  static uint16_t u16_Main_State = 0;
                                                  //Initialize Main State
  static uint16_t u16_Request_Timer = 0;
                                                   //Initialize Request Timer
   //Timer Routine For Automatic Activation of Requests
  if(Inno3ProClk.clock_HasTimeElapsedMs(u16_Request_Timer,1000)) //Delay Time
  {
    u16_Main_State++;
                                        //Change State
    u16_Request_Timer = Inno3ProClk.clock_GetTimeStampMs(); //Reset Timer
  }
  // Main Loop States
   switch(u16_Main_State)
   {
        case 0:
        u16_Main_State = 1;
        break:
    case 1: //Activate 5V Configuration
        // CV = 5V and CC = 3.1A
        Inno3ProApp.Inno3Pro_PD_Write_VI(5,3.1);
        break:
    case 2: //Activate 9V Configuration
        Inno3ProApp.Inno3Pro_PD_Write_VI(9,3.1);
        break;
    case 3: //Activate 15V Configuration
        Inno3ProApp.Inno3Pro_PD_Write_VI(15,3.1);
        break;
    case 4: //Activate 20V Configuration
        Inno3ProApp.Inno3Pro_PD_Write_VI(20,3.1);
        break;
    case 5: //Activate 3.3V Configuration
        Inno3ProApp.Inno3Pro_PD_Write_VI(3.3,3.1);
        break;
    default:
        u16_Main_State = 1;
        break;
  }
}
```

Figure 11. Inno3-Pro_PDOs.ino Code



InnoSwitch4-Pro Examples

Example 1 – Inno4Pro_Basic.ino

Inno3Pro_Basic.ino sketch implements the essential commands to run the InnoSwich3-Pro IC. The adapter will output 5V 3.1A while using this code. There are five commands in this sketch to note:

- Inno4Pro_Initialization(); Function for initializing the InnoSwitch4-Pro device
- Inno4Pro_Write_VI(); Function for setting the output voltage and current
- Inno4Pro_Write_Volt_Peak(); Sets the knee voltage (V_{KP})
- Inno4Pro_Vbus_Switch_Control(); Controls the BUS switch

Example 2 – Inno4Pro_PDOs.ino

This sketch cycles through the multiple output voltages. This mimics the USBPD standard PDO's for 60W adapters. Main functions used:

- Inno4Pro_Initialization(); Initializes InnoSwitch4-Pro
- Inno4Pro_Write_Cable_Drop_Comp(); Sets the cable drop voltage in mV
- Inno4Pro_Write_Volt_Peak() Sets the knee voltage (VKP)
- Inno4Pro_Vbus_Switch_Control() Controls the BUS switch
- clock_HasTimeElapsedMs(); Returns 1 when a certain amount of time in milliseconds has elapsed.
- Clock_GetTimeStampMs(); Returns the current time in milliseconds
- Inno4Pro_PD_Write_VI(); Sets the output voltage and current



Figure 13. Inno4Pro_PDOs.ino Output Voltage Waveform











```
//Step 1 : Add the Header Files
#include <Drv_Rtc.h>
#include <Drv_i2c.h>
#include <InnoProBase.h>
#include "Inno4Pro.h"
#include "Inno4ProConfig.h"
//Step 2 : Create the class instance
InnoProBase_Rtc Inno4ProClk;
Inno4Pro_Application Inno4ProApp;
//Step 3 : Write Initial Commands to InnoPro
void setup()
{
           Inno4ProApp.Inno4Pro_Initialization();
           Inno4ProApp.Inno4Pro_Write_Cable_Drop_Comp(300);
           Inno4ProApp.Inno4Pro_Write_Volt_Peak(24);
           Inno4ProApp.Inno4Pro_Vbus_Switch_Control(1);
}
//Step 4 : Call the Functions on the Main Loop
void loop()
{
  // Main Loop Variables
  static uint16_t u16_Main_State = 0;
                                              //Initialize Main State
  static uint16_t u16_Request_Timer = 0; //Initialize Request Timer
  //Timer Routine For Automatic Activation of Requests
  if(Inno4ProClk.clock_HasTimeElapsedMs(u16_Request_Timer,1000))
  {
    u16_Main_State++;
                                       //Change State
   u16_Request_Timer = Inno4ProClk.clock_GetTimeStampMs ();
  }
  // Main Loop States
  switch(u16_Main_State)
  {
    case 0:
        u16_Main_State = 1;
        break;
    case 1: //Activate 5V Configuration
        Inno4ProApp.Inno4Pro_PD_Write_VI(5,3.1);
        break;
    case 2: //Activate 9V Configuration
        Inno4ProApp.Inno4Pro_PD_Write_VI(9,3.1);
        break:
    case 3: //Activate 15V Configuration
        Inno4ProApp.Inno4Pro_PD_Write_VI(15,3.1);
        break;
    case 4: //Activate 20V Configuration
        Inno4ProApp.Inno4Pro_PD_Write_VI(20,3.1);
        break;
    case 5: //Activate 3.3V Configuration
        Inno4ProApp.Inno4Pro_PD_Write_VI(3.3,3.1);
        break;
    default:
        u16_Main_State = 1;
        break;
  }
```

Figure 15. Example 2 - Inno4Pro_PDOs.ino Code



Source Files

Name	Date modified	Туре	Size
₩ Drv_i2c	16/12/2021 2:34 pm	CPP File	4 KB
📔 Drv_i2c	16/12/2021 2:34 pm	H File	4 KB
📔 Drv_Rtc	16/12/2021 2:34 pm	CPP File	3 KB
📔 Drv_Rtc	16/12/2021 2:34 pm	H File	4 KB
📔 Inno3Pro	22/12/2021 4:11 pm	CPP File	45 KB
📔 Inno3Pro	22/12/2021 4:11 pm	H File	67 KB
📔 Inno3ProConfig	23/12/2021 9:19 am	H File	26 KB
📔 Inno4Pro	06/01/2022 11:09 am	CPP File	50 KB
📔 Inno4Pro	22/12/2021 4:11 pm	H File	69 KB
📔 Inno4ProConfig	23/12/2021 9:19 am	H File	28 KB
📔 InnoProBase	16/12/2021 2:34 pm	CPP File	10 KB
📔 InnoProBase	16/12/2021 2:34 pm	H File	14 KB
📔 LcdKeypad	16/12/2021 2:34 pm	CPP File	4 KB
📔 LcdKeypad	16/12/2021 2:34 pm	H File	3 KB

API - Handles command sequences, timings, register settings, threshold calculations, parity implementations, telemetry, and etc. Code core used by both InnoSwitch3-Pro and InnoSwitch4-Pro

- InnoProBase.h •
- InnoProBase.cpp
- Code core limited to InnoSwitch3-Pro
 - Inno3Pro.h ٠
 - Inno3Pro.cpp
- Code core limited to InnoSwitch4-Pro
 - Inno4Pro.h
 Inno4Pro.cr
 - Inno4Pro.cpp
- Code core for controlling LCD Keypad Arduino Shield
 - LcdKeypad.h •
 - LcdKeypad.cpp •

InnoSwitch Driver – Manages I²C packet format based on InnoSwitch3-Pro/InnoSwitch4-Pro datasheet for write and read transactions. Arduino Wire library was used as the lower level library.

- Drv_I2C.h ٠
- Drv_I2C.cpp •

Clock Driver – A module for generating delays and timings

- Drv_Rtc.h ٠
- Drv_Rtc.cpp



The figure below shows how each of the layers interact with each other. The application layer consists of the InnoSwitch3-

Pro/InnoSwitch4-Pro Arduino sketches that implement the function of the InnoSwich3-Pro/InnoSwitch4-Pro and Clock Driver functions.





Building the Project

Board Selection

- 1. Go to *Tools menu > Board:* and select the Arduino device used.
- 2. Select also the active COM port number from *Tools menu* >

Port which determines which USB port the Arduino board is connected.

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}	WiFi101 / WiFiNINA Firmware Updater	-	-	
void loop()	Board: "Arduino Uno"	;		Boards Manager
// put yo	Port: "COM9 (Arduino Uno)"	2		Arduino Yún
	Get Board Info		٠	Arduino Uno
}	Programmer: "AVRISP mkll" Burn Bootloader	;		Arduino Duemilanove or Diecimila Arduino Nano Arduino Mega or Mega 2560

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}	v	ViFi101 / WiFiNINA Firmware Updater			
<pre>void loop()</pre>	B	oard: "Arduino Uno"	>		
// put yo	Р	ort: "COM9 (Arduino Uno)"	>		Serial ports
	G	et Board Info		_	COM3
}	Р	rogrammer: "AVRISP mkll"	X	~	COM9 (Arduino Uno)
	B	urn Bootloader			



Sketch Upload

- 1. Select the desired sketch to use from *File menu > Examples > InnoSwitch3-Pro and InnoSwitch4-Pro Library.* Click on the Verify icon on the upper left corner of the IDE.
- An indicator will show on the bottom of the screen that says "Done compiling" along with the amount of memory used by
 Inno3Pro_Basic | Arduino 1.8.16

the sketch.

 Click on the Arrow icon beside the Verify button to upload the compiled sketch onto the Arduino board. Once done, an indicator on top of the debug log will show "Done Uploading".

	🛃 Verify
Inno3Pro_Basic	
/** InnoSwitch	13-Pro Example Application
Company:	Power Integrations
Summary:	This is to demonstrate the Basic usage of InnoSwitch3-Pro Arduino Library
@author	CS/JV - PIPH Applications
Ødate	December 08, 2021
Copyright	(C) 2021 Power Integrations. All rights reserved.
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	Upload
Inno3Pro_Basic	
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Company:	Power Integrations
Summary:	This is to demonstrate the Basic usage of InnoSwitch3-Pro Arduino Library
Qauthor	CS/JV - PIPH Applications
@date	December 08, 2021
Copyright	(C) 2021 Power Integrations. All rights reserved.
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Hardware Setup

This section demonstrates the use of the Arduino library in controlling the InnoSwitch3-Pro device. The sketch used in this example is



Inno3_Basic.ino where it initializes the InnoSwitch3-Pro to output 5V and 3.1A. Remove jumpers J6 and J7 on the RDK-641 board. Connect the I^2C lines of the Arduino board to the RDK-641 as shown in the figure below. Upon power up of RDK-641, the sketch is uploaded to the Arduino board. The output of the RDK-641 should be 5V with a 3.1A current limit.

InnoSwitch4-Pro setup uses the RDR-961 board instead of the RDK-641. Inno4Pro_PDOs.ino sketch changes the output voltage every second from 5 V> 9 V> 15 V> 20 V> 5 V through the use of multiple Inno4Pro_PD_Write_VI() commands.



Doxygen Documentation

There are compiled HTML (.chm) and HTML (.html) files in the Documentation folder. These files contain the documentation of the InnoSwitch3-Pro and InnoSwitch4-Pro Arduino Library. It contains brief descriptions on how to use each function in the API and core drivers. The examples in the document



shows a brief overview on how the code works as well as a guide on how to use each sketch.

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Appendix

Register Definition

I²C Slave Address The InnoSwitch3-Pro and InnoSwitch4-Pro 7-bit slave address is 0x18 (7'b001 1000).





I²C Protocol Format

3-Byte Write Commands: [PI_SLAVE_ADDRESS][W][A][PI_COMMAND][A][Byte][A] or [PI_SLAVE_ADDRESS][W][A][PI_COMMAND][A][Low Byte][A][High Byte][A]



2-Byte Read Commands:

[PI_SLAVE_ADDRESS][W][A][PI_COMMAND][A][START_TELEMETRY_REGISTER_ADDRESS][A][END_TELEMETRY_REGISTER_ADDRESS][A] [PI_SLAVE_ADDRESS][r][A][PI Slave responds Low Byte][a][PI Slave responds High Byte][na]





Revision	Notes	Date
А	Initial release.	01/20/23

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